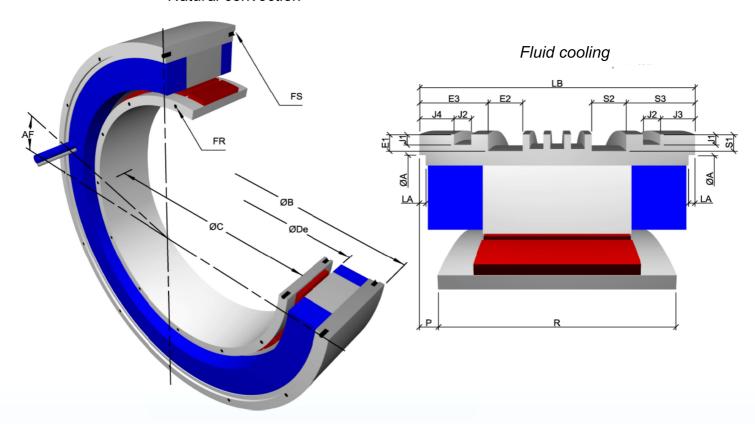
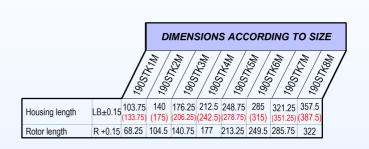
MOTORS 190 STK

Natural convection



DIMENSIONS FOR ALL 190 STK		
Housing internal centering diameter	A H8	172
Angle wire output / tapped holes	AF	22°30'
Housing external centering diameter (fluid cooling)	B f8	193
Housing external centering diameter (natural convection)	B f8	190
Rotoric internal centering diameter	C H7	72
Housing internal diameter	De	98
Depth of fluid front input / output groove	E1	3
Width of fluid front input / output groove	E2	11.7
Position of fluid front I/O groove	E3	15.5 (45.5)
Rotoric fixation holes	FR	8xM5 sur Ø80
Housing fixation holes	FS	8xM5 sur Ø180
O-ring groove depth	J1	2.3
O-ring groove width	J2	4
Position of rear o-ring groove	J3	5
Position of front o-ring groove	J4	10 (40)
Depth of housing internal centering diameter	LA	2
Alignment rotor / housing	P ± 0.1	23 (53)
Maximum rotoric contact diameter	Pmax	94
Depth of fluid rear I/O groove	S1	3
Width of fluid rear I/O groove	S2	11.7
Position of fluid rear I/O groove	S3	10.5
GRATION:	- 55	10.0



The dimensions in $\overline{\text{red}}$ in the table are valid in the case of a rated current greater than 53 A and class 6 shielded cable output

We also offer the possibility of not shielded output wires without need of stator length increase.

INTEGRATION:

- The cables are made of PU, class 6, foreseen for cable-bearing chains, 2 mt standard length, copper square section according rated current.
- ✓ Rotor / housing alignment (P) has to be executed within +/- 0.1 mm. Optionally, we can supply a mounting tool for achieving that alignment in case of assembly without possibility of accurate alignment.
- ✓ Thermal devices cable consists of 2 shielded pairs 2x2x0.25mm² section, 7 mm max external diameter.
- ✓ (De) represents: 1- The maximum diameter passing inside the housing.
 - 2- The minimum diameter necessary for rotor assembly.
- ✓ (Pmax) diameter for pieces in contact with the rotor must never be exceeded.
- ✓ Tapped holes on each side of rotor and housing are angularly aligned.
- ✓ Cable positioning (AF) is theoretical. Leave a free room with a +/- 10 arc degrees tolerance around that position, on a 50 mm height from the housing side, for avoiding to stress the cables at the motor output.
 - Do not tighten, twist or bend the power cable on the first 50 mm from motor side. Clamp the power cable after those 50 mm.
- ✓ When designing the assembly, take care to insure a perfect contact between housing and user's bore for avoiding thermal problems.
- ✓ For housing mounting, use either external centering diameter (B) or internal centering diameters (A).
- ✓ For execution tolerances (perpendicularity, concentricity...), please consult us.
- ✓ Fluid input and output pipes have to be placed at the opposite of wire outputs on the same axial plane.
- ✓ O-ring grooves designed for 3 mm diameter o-rings.

A full integration handbook can be supplied to our customers upon request For further information or specific request about our motors, feel free to contact us.

STK motors